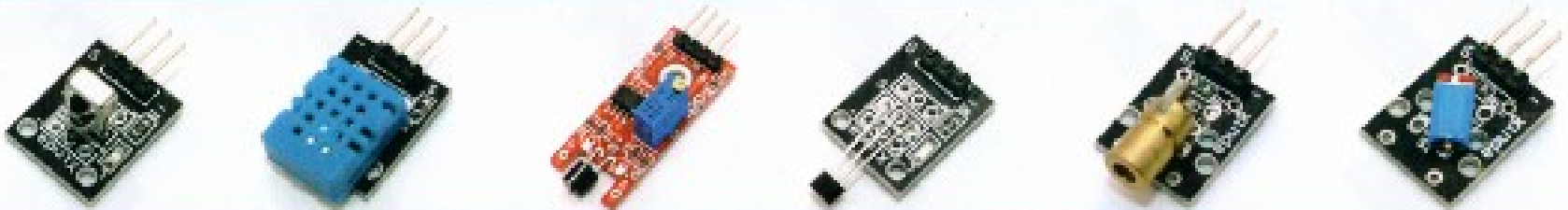


# “Kit de 37 sensores”

## 37 SENSOR KIT



**Maker Faire: Make the world more intelligent!**

Rogelio Ferreira Escutia

# Contenido

## 37 SENSOR KIT

Maker Faire: Make the world more intelligent!

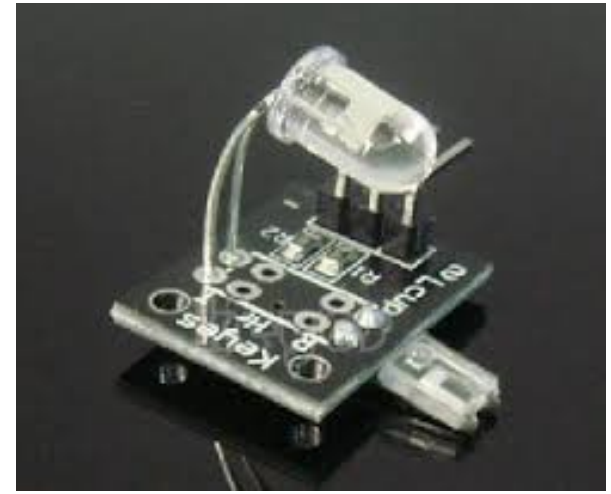
 <p>JOYSTICK</p>	 <p>FLAME</p>	 <p>RGB LED</p>	 <p>HEARTBEAT</p>	 <p>2PCS LIGHT CUP</p>	 <p>HALL MAGNETIC</p>
 <p>RELAY</p>	 <p>LINEAR HALL</p>	 <p>SMD RGB</p>	 <p>7 COLOR FLASH</p>	 <p>TILT SWITCH</p>	 <p>19820 TEMP</p>
 <p>BIG SOUND</p>	 <p>TOUCH</p>	 <p>TWO-COLOR</p>	 <p>LASER EMIT</p>	 <p>BALL SWITCH</p>	 <p>ANALOG TEMP</p>
 <p>SMALL SOUND</p>	 <p>DIGITAL TEMPERATURE</p>	 <p>MINI TWO-COLOR</p>	 <p>BUTTON</p>	 <p>PHOTORESISTOR</p>	 <p>IR EMISSION</p>
 <p>TRACKING</p>	 <p>BUZZER</p>	 <p>REED SWITCH</p>	 <p>SHOCK</p>	 <p>TEMP AND HUMIDITY</p>	 <p>IR RECEIVER</p>
 <p>AVOIDANCE</p>	 <p>PASSIVE BUZZER</p>	 <p>MINI SWITCH</p>	 <p>ROTARY ENCODERS</p>	 <p>ANALOG HALL</p>	 <p>TAP MODULE LIGHT BLOCKING</p>



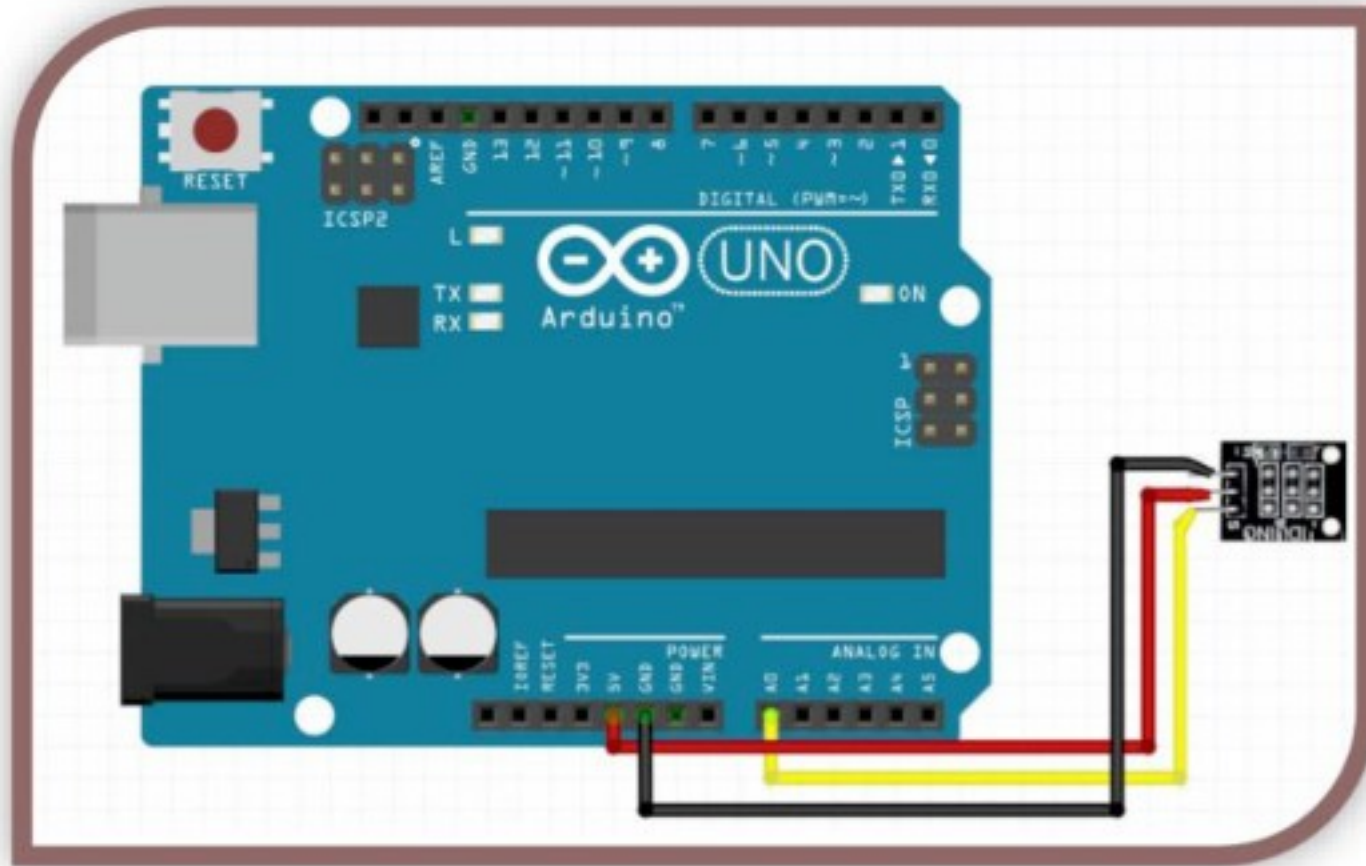
# Conexión y Programación de Sensores

# Heartbeat

- ?



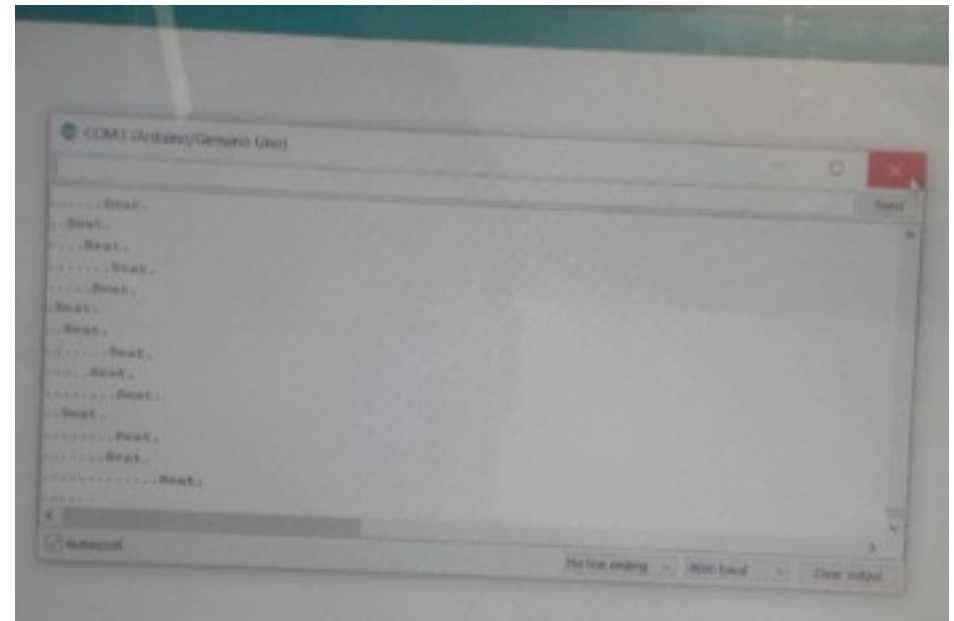
# Heartbeat



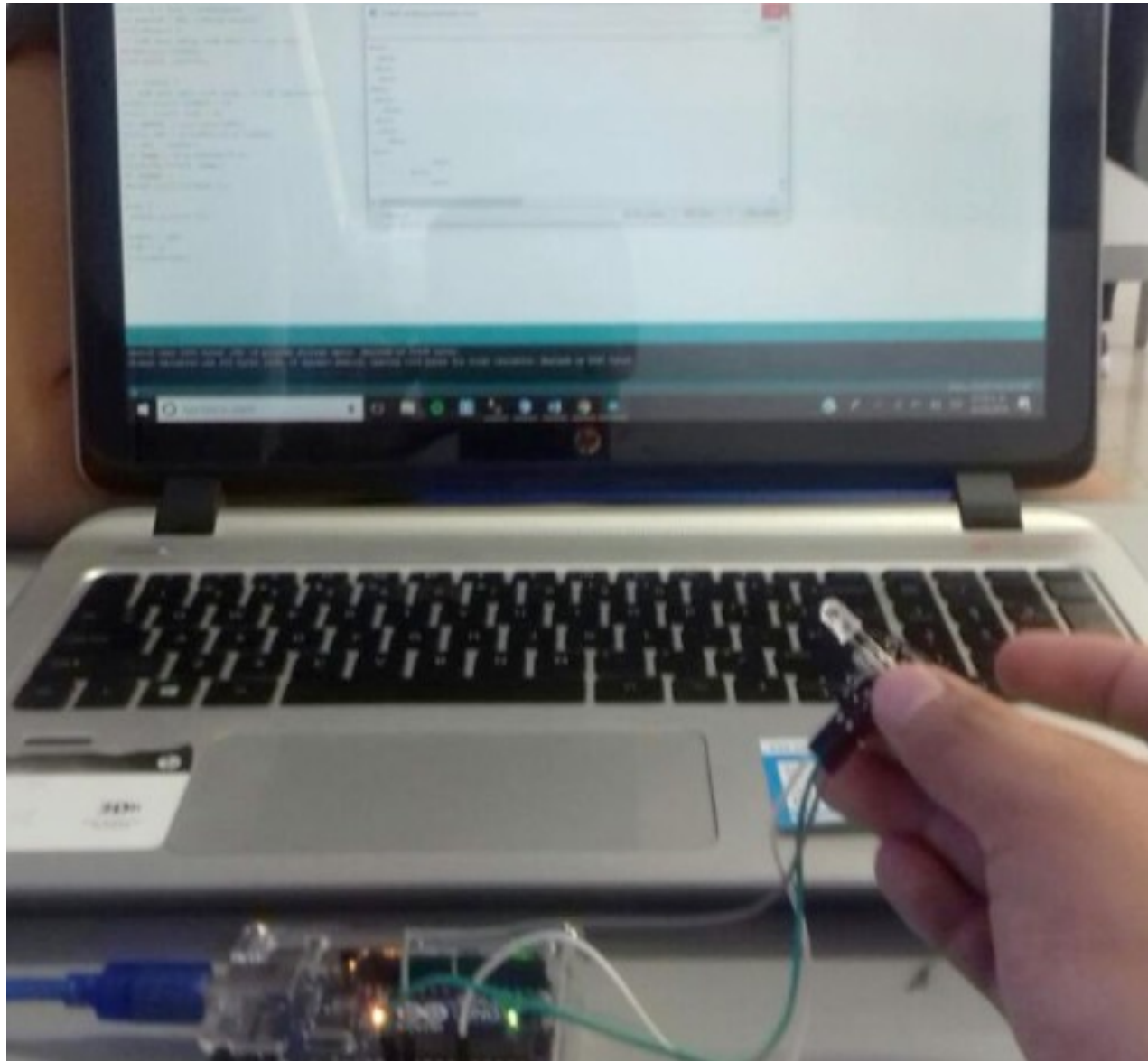
# Heartbeat

Heartbeat §

```
double a = 0.75; //Alpha
double c = 0.0; //Difference
int period = 20; //Delay period
void setup() {
  // put your setup code here, to run once:
  Serial.begin(9600);
  pinMode(13, OUTPUT);
}
void loop() {
  // put your main code here, to run repeatedly:
  static double oldVal = 0;
  static double oldC = 0;
  int rawVal = analogRead(A0);
  double val = a*oldVal+(1-a)*rawVal;
  c = val - oldVal;
  int temp = (c<0.0&&oldC>0.0);
  digitalWrite(13, temp);
  if (temp) {
    Serial.println("Beat.");
  }
  else {
    Serial.print(".");
  }
  oldVal = val;
  oldC = c;
  delay(period);
}
```



# Heartbeat



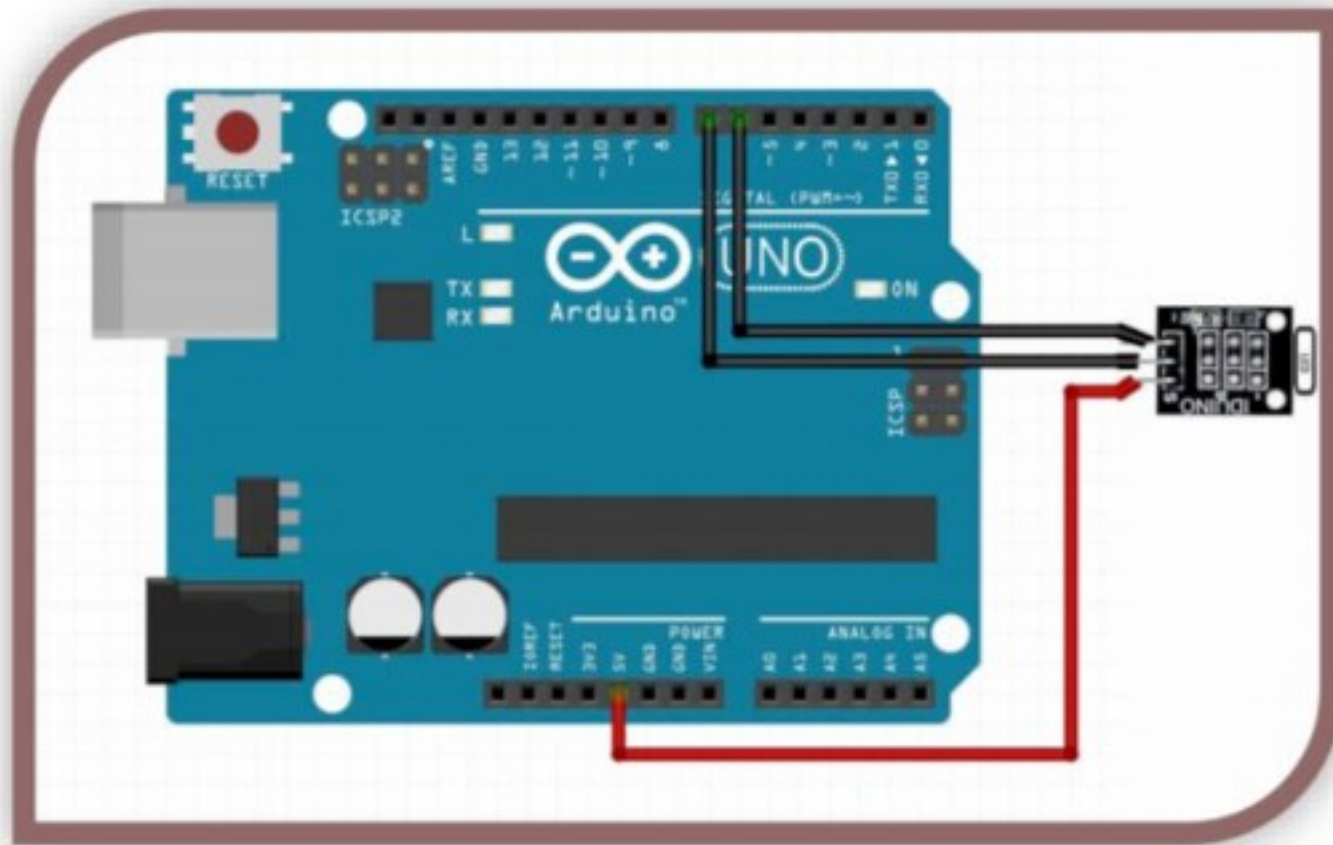
# Color Light

- ?



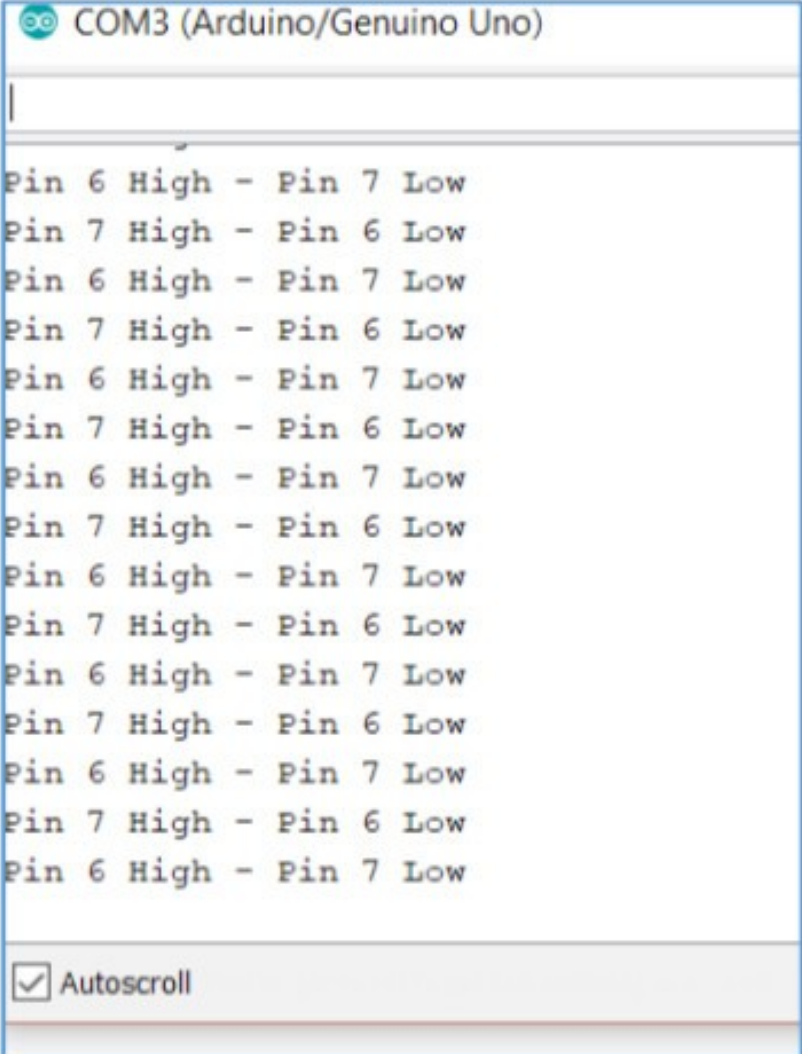


# Color Light



# Color Light

```
void setup() {
  // put your setup code here, to run once:
  Serial.begin(9600);
  pinMode(7, OUTPUT);
  pinMode(6, OUTPUT);
}
void loop() {
  // put your main code here, to run repeatedly:
  digitalWrite(7, HIGH);
  digitalWrite(6, LOW);
  Serial.println("Pin 7 High - Pin 6 Low");
  delay(1000);
  digitalWrite(6, HIGH);
  digitalWrite(7, LOW);
  Serial.println("Pin 6 High - Pin 7 Low");
  delay(1000);
}
```

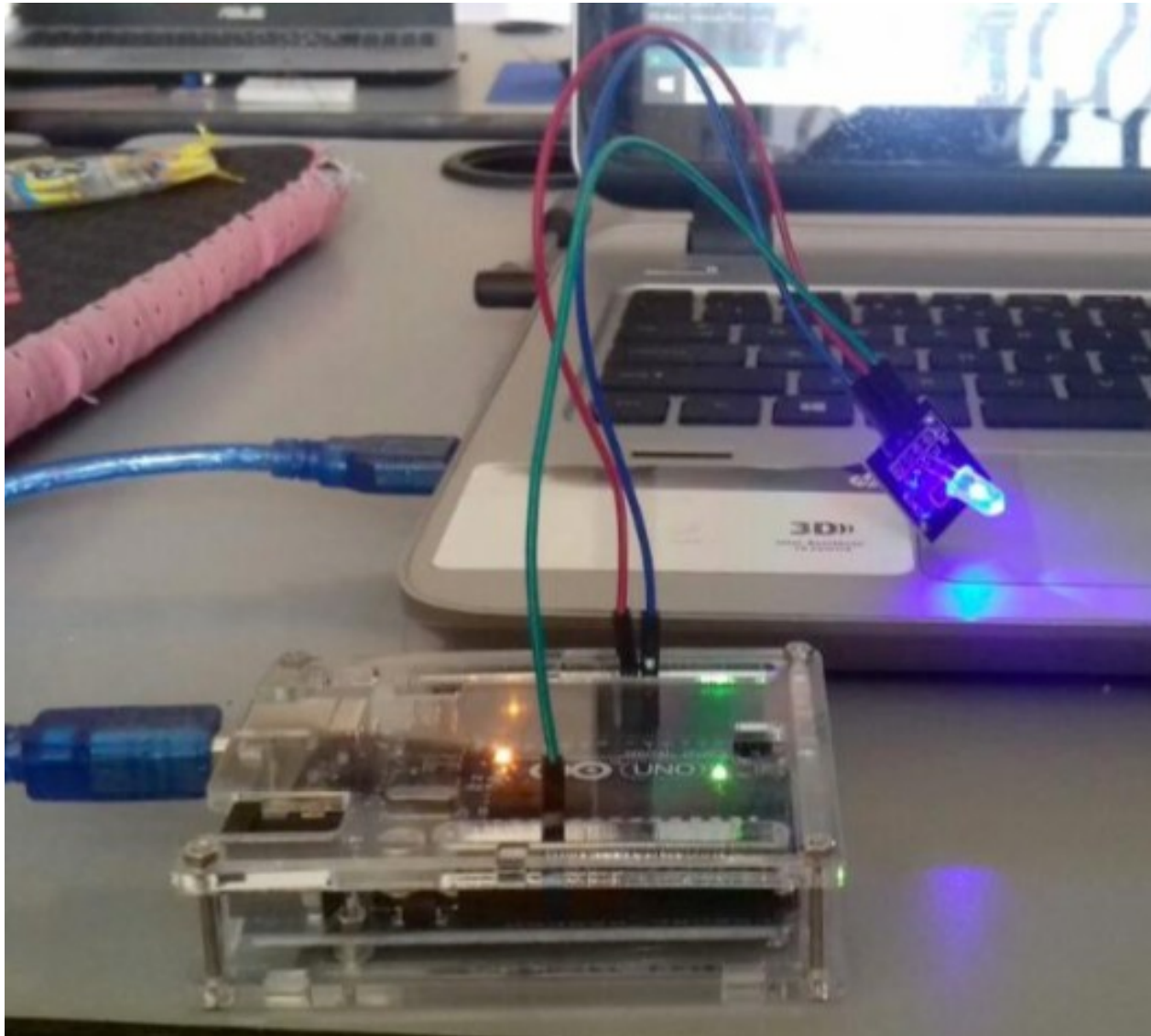


```
COM3 (Arduino/Genuino Uno)

Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low
Pin 7 High - Pin 6 Low
Pin 6 High - Pin 7 Low

 Autoscroll
```

# Color Light

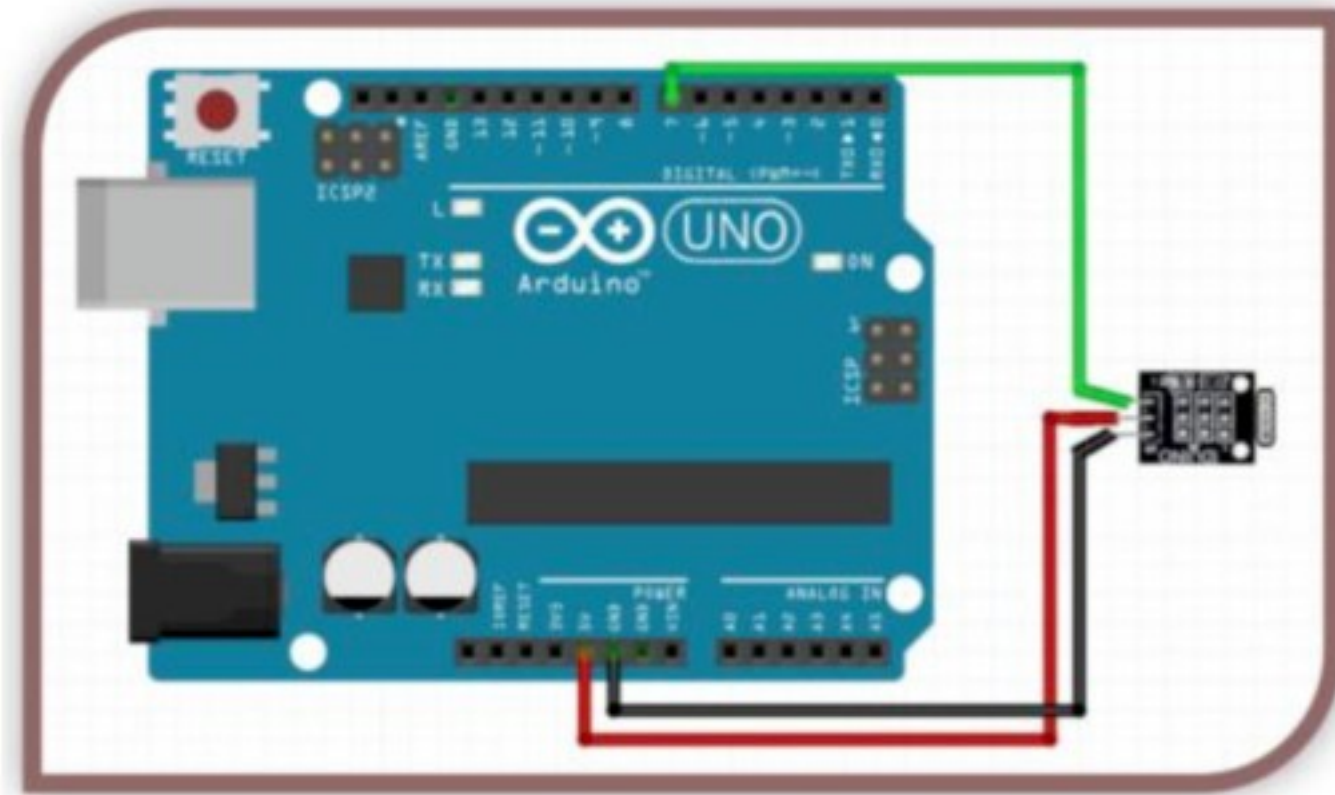


# Tilt Switch

- ?

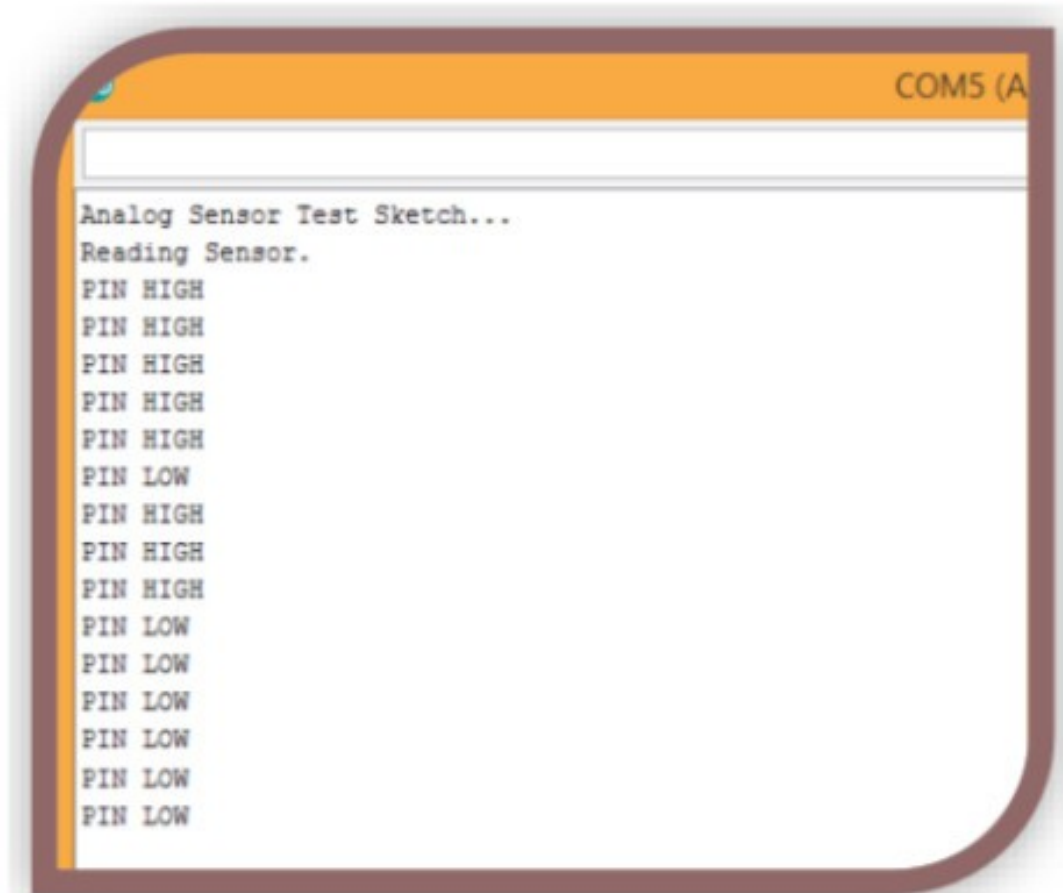


# Tilt Switch



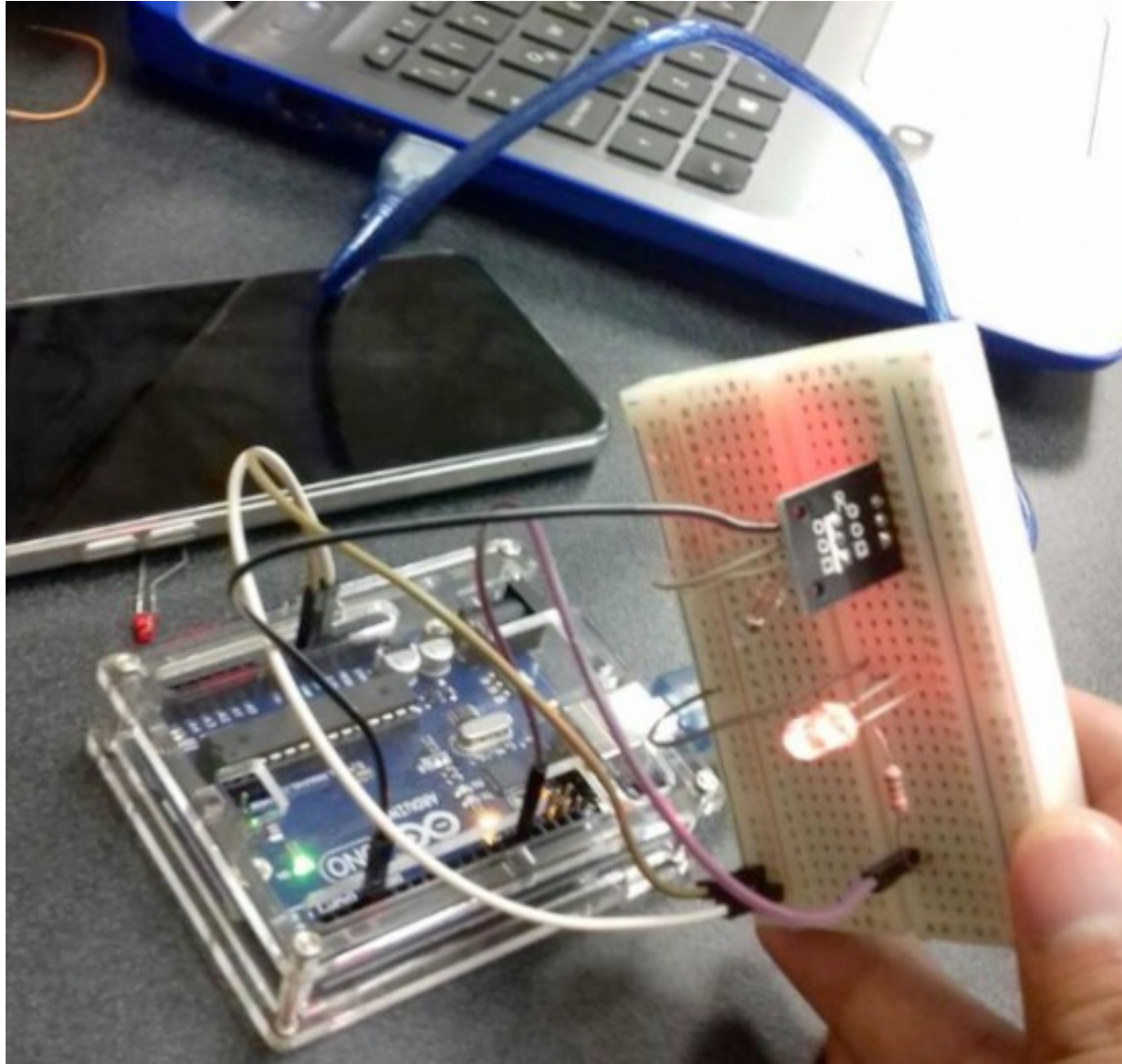
# Tilt Switch

```
pinMode(3, OUTPUT);
}
void loop() {
  // put your main code here, to run repeatedly
  merc1Val = digitalRead(2);
  if (merc1Val == 1 && merc1LastVal == 0) {
    light1Val -= light1Val / 8;
    light2Val += light2Val / 8;
    light1State = 1;
    merc1LastVal = 1;
  }
  if (merc1Val == 0 && merc1LastVal == 1) {
    light1Val += light1Val / 8;
    light2Val -= light2Val / 8;
    light1State = 0;
    merc1LastVal = 0;
  }
  if (light1State) {
    light1Val--;
    light1Val = constrain(light1Val, 0, 255);
    light2Val++;
    light2Val = constrain(light2Val, 0, 255);
    analogWrite(3, light1Val);
    analogWrite(5, light2Val);
  }
  else {
    light1Val++;
    light1Val = constrain(light1Val, 0, 255);
    light2Val--;
    light2Val = constrain(light2Val, 0, 255);
    analogWrite(3, light1Val);
    analogWrite(5, light2Val);
  }
}
```





# Tilt Switch





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